

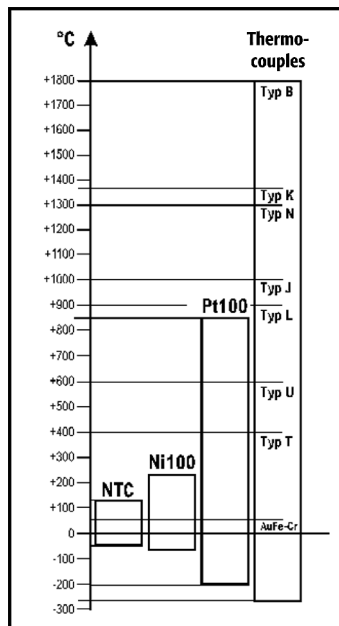
## 3.1 Temperature sensors

### 3.1.1 Selecting the Right Temperature Sensor

Selecting the right type of temperature sensor depends on your measuring task. For example, thermocouples, resistor-based sensors (Pt100 and Ntc) and pyrometers (infrared sensors) are available.

#### Rule of Thumb:

1. Thermocouples are very fast and provide a large measuring range.
2. Resistor-based sensors are more accurate but slower.
3. Ntc sensors are very fast, accurate, but they have a limited measuring range.
4. Infrared sensors do not contact the device under test and they have very small time constants, but they depend on the emission grade.
5. The larger the measuring range, the more universal the possible range of applications..



#### Selection Criteria:

Select the temperature sensor that suits your measuring task according to the criteria below:

- Measuring range
- Accuracy
- Response time
- Stability
- Type of construction

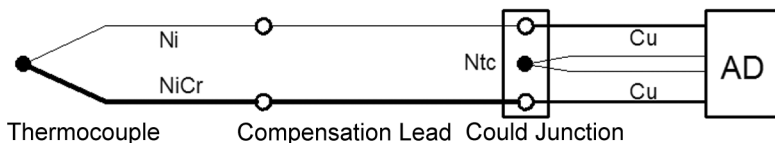
#### Types:

- Surface sensors for good heat conductors
- Surface sensors for poor heat conductors
- Immersion probes for liquids
- Immersion probes for air and gases
- Insertion probes
- High temperature sensors (note measuring range)
- Infrared sensor for non-contact measurements
- Sword probe for paper, cardboard, tobacco and textiles

### 3.1.2 Thermocouples

#### Measuring Principle

Thermocouples consist of two spot-welded wires of different metals or alloys. The thermoelectric effect at the contact surface is used to measure temperatures. It causes a relatively small thermoelectric voltage that depends on the temperature difference between the measuring point and the connecting terminals. A range of thermocouples are available that can be distinguished by their temperature range, sensitivity and particularly the compatibility with the medium of measurement.

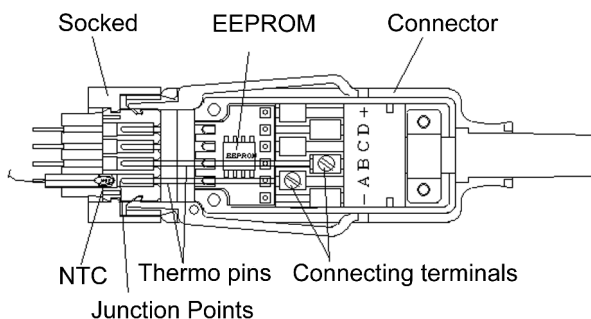


#### Basic Values IEC 584-1:1995 (ITS90)

temperature °C	NiCr-Ni type K mV	NiSi type N mV	Fe-CuNi type J mV	Cu-CuNi type T mV	PtRh10-Pt type S mV	PtRh30-Pt type B mV	AuFe-Cr mV
-270	-	-4.345	-	-6.258	-	-	-4.714
-200	-5.891	-3.990	-7.890	-5.603	-	-	-3.709
-100	-3.554	-2.407	-4.633	-3.379	-	-	-2.039
0	0	0	0	0	0	0	0
100	+4.096	+2.774	+5.269	+4.279	+0.646	+0.033	
200	+8.138	+5.913	+10.779	+9.288	+1.441	+0.178	
300	+12.209	+9.341	+16.327	+14.862	+2.323	+0.431	
400	+16.397	+12.974	+21.848	+20.872	+3.259	+0.787	
500	+20.644	+16.748	+27.393		+4.233	+1.242	
600	+24.905	+20.613	+33.102		+5.239	+1.792	
700	+29.129	+24.527	+39.132		+6.275	+2.431	
800	+33.275	+28.455	+45.494		+7.345	+3.154	
900	+37.326	+32.371	+51.877		+8.449	+3.957	
1000	+41.276	+36.256	+57.953		+9.587	+4.834	
1100	+45.119	+40.087	+63.792		+10.757	+5.780	
1200	+48.838	+43.846	+69.553		+11.951	+6.786	
1300	+52.410	+47.513			+13.159	+7.848	
1400					+14.373	+8.956	
1500					+15.582	+10.099	
1600					+16.777	+11.263	
1700					+17.947	+12.433	
1800						+13.591	

## Cold Junction

Thermocouples only allow for a determination of the absolute temperature when the temperature of the connecting terminals is kept at a known temperature (e.g. using ice water or a thermostat) or when this cold junction temperature is measured continuously. ALMEMO® devices contain a miniature NTC temperature sensor in the contact of the ALMEMO® socket to measure the exact temperature of the junction point from thermocouple to copper. ALMEMO® connectors with thermomaterial pins are available for use with the most popular thermocouple NiCr-Ni, which means that the junction point directly neighbours the temperature sensor. Each temperature difference between junction point and temperature sensor causes an error of measurement. This must be considered with other thermocouples, especially when very hot or cold sensors are inserted into the socket. In copper plugs the junction point is located in the screw terminals. The correct temperature is only measured when the screw terminal and the NTC sensor have the same temperature.



The characteristics of thermocouples are non-linear. Therefore, the temperature of the junction point must not be added to the measured temperature for determining the absolute temperature. The voltage that corresponds to the junction point temperature of the thermocouple used must be added to the voltage that corresponds to the measured value.

*Example for NiCrNi thermocouple:*

	Voltage		Temperature
Measured value:	24.902 mV	->	600.0 °C
Junction point temperature:	+ 1.000 mV	<-	25.0 °C
Corrected measured value:	25.902 mV	->	<b>623.5 °C</b> not 625 °C!

The user does not need to care about this calculation because it is performed by the ALMEMO® measuring instrument. However, an understanding of the relations is very helpful when measurements with external junction point (see also 6.7.3) are performed.

## Compensation Lines

Compensation lines that are lower in costs and easier to handle are often used as an extension for thermocouples. However, the compensation lines can vary with their thermoelectric voltage from the thermocouple. To keep the measuring errors within close tolerances, the contacts for connection to the thermocouple and to the measuring device should be kept at the same temperature.



Even larger errors occur when the type of the compensation line does not fit to the thermocouple or when the compensation line is wrongly poled. This should be avoided at all costs.

### Application

Because of their low weight thermocouple sensors provide a high indication speed. Therefore, they especially suit the requirements for reference measurements in production, test fields and laboratories. Jacketed thermocouples with diameters of less than 0.5mm are very beneficial as they are internally isolated and do not provide an electrical connection to the device under test. They are flexible and can even be soldered. However, the bend radius selected must not be too small (at minimum 5x diameter). Generally, too much mechanical stress should be avoided with thermocouples as the characteristics can change due to the structural changes.



Measuring operations using bare, non-insulated thermo-wire sensors can only be recommended in air or in / on electrically insulating materials (e.g. plastics). For measuring operations on electrically conductive materials with (high) electrical potential, insulated jacket thermocouple sensors should preferably be used. Alternatively, thermo-wire sensors can be connected, electrically isolated, via the NiCr-Ni measuring module ZA9920AB; (see 4.2.8.3).

### Accuracy of Measurement

The thermocouple sensors are available in two tolerance classes, according to DIN/IEC 584-2. The following limits are applicable for type K (larger value of each):

Class 1:  $\pm 1.5^{\circ}\text{C}$  or  $\pm 0.004 \times |t|$   $(-40 \dots 1000^{\circ}\text{C})$

Class 2:  $\pm 2.5^{\circ}\text{C}$  or  $\pm 0.0075 \times |t|$   $(-40 \dots 1200^{\circ}\text{C})$

The T<sub>max</sub> values given in the technical data refer to the tip of the sensor. The sensor grips and cables are stable for temperatures up to 80°C. Heat-resistant cables are available for use at higher ambient temperatures.

### 3.1.3 Resistor-based Sensors

#### Measuring Principle

The increase in resistance at increasing temperatures is utilised at the **Pt100 sensors**. The measuring resistor is fed with a constant current and the voltage drop at the resistor is measured as a function of the temperature. Due to the small resistance variation ( $0.3$  to  $0.4\Omega/^{\circ}\text{C}$ ) the 4-conductor circuit should always be used to exclude any influences from the lead wires.

In contrast **NTC sensors** (thermistors) have a significant higher resistance and a negative temperature coefficient, i.e. the resistance decreases when the temperature increases.

#### Accuracy of Measurement

Pt100 sensors are, as standard, used with class B (DIN/IEC 751) measuring resistors (surcharge for class A or 1/5DIN accuracy). The accuracy data of the normalised NTC sensors are based on manufacturer specifications. The  $T_{\max}$  values given in the technical data refer to the tip of the sensor. The sensor grips and cables are stable for temperatures up to  $80^{\circ}\text{C}$ . Heat-resistant cables are available for use at higher ambient temperatures.

Description	Range	Maximum Deviation		
NTC-element (10K at $25^{\circ}\text{C}$ )	$-20$ to $0^{\circ}\text{C}$	$\pm 0.4\text{ K}$		
	$0$ to $70^{\circ}\text{C}$	$\pm 0.1\text{ K}$		
	$70$ to $125^{\circ}\text{C}$	$\pm 0.6\text{ K}$		
Meas. resistances		class B	class A	1/5 DIN
Pt 100 $\Omega$	at $-200^{\circ}\text{C}$	$\pm 1.3\text{ K}$		
	at $-100^{\circ}\text{C}$	$\pm 0.8\text{ K}$		
	at $-50^{\circ}\text{C}$		$\pm 0.25\text{ K}^*$	
	at $0^{\circ}\text{C}$	$\pm 0.3\text{ K}$	$\pm 0.15\text{ K}$	$\pm 0.06\text{ K}$
	at $+100^{\circ}\text{C}$	$\pm 0.8\text{ K}$	$\pm 0.35\text{ K}$	$\pm 0.16\text{ K}$
	at $+200^{\circ}\text{C}$	$\pm 1.3\text{ K}$	$\pm 0.55\text{ K}$	$\pm 0.26\text{ K}$
	at $+300^{\circ}\text{C}$	$\pm 1.8\text{ K}$	$\pm 0.75\text{ K}$	$\pm 0.36\text{ K}$
	at $+400^{\circ}\text{C}$	$\pm 2.3\text{ K}$		

\* only for Sheathed sensors with diameter  $d=2\text{mm}$  or bigger

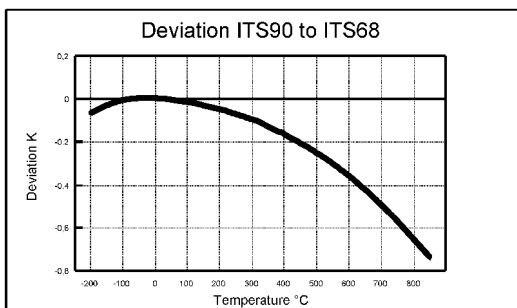
Pt100 sensors FP Axxx are, as standard, provided with the measuring range Pt100-1 (resolution  $0.1\text{K}$ ). The range Pt100-2 (resolution  $0.01\text{K}$ ) can, alternatively, be programmed on the first or, in addition, on the second channel.

**New:** Measuring range Pt100-3 (resolution  $0.001\text{K}$ ) at  $0$  to  $65^{\circ}\text{C}$  (Only with devices version V6: 2690-8, 2890-9, 8590-9, 8690-9A, 5690-1/-2)

#### International Temperature Scale ITS 90

With the implementation of the new international temperature scale 1990 into German law, the previous temperature scale IPTS-68 is no longer valid and the

new standards of ITS-90 (DIN/IEC) must be applied. The characteristics of the Pt100 sensors show the deviations below that must be considered at calibrations and comparisons.



Temperature °C	Pt100 (ITS90) R(T) [Ω]	Pt100 (IPTS68) R(T) [Ω]	Temperature °C	NTC R(T) [Ω]
-200	18,52	18,49	-50	670100
-150	40,00	39,71	-40	336500
-100	60,26	60,25	-30	177000
-50	80,31	80,31	-20	97080
0	100,00	100,00	-10	55330
50	119,40	119,40	0	32650
100	138,51	138,50	10	19900
150	157,33	157,32	20	12490
200	175,86	175,84	25	10000
250	194,10	194,07	30	8057
300	212,05	212,02	40	5327
350	229,72	229,67	50	3603
400	247,09	247,04	60	2488
450	264,18	264,11	70	1752
500	280,98	280,90	80	1255
550	297,49	297,39	90	915,3
600	313,71	313,59	100	678,3
650	329,64	329,51	110	510,3
700	345,28	345,13	120	389,3
750	360,64	360,47	130	300,93
800	375,70	375,51	140	235,27
850	390,48	390,26	150	185,97

### 3.1.4 Wet Bulb Globe Temperature Measurement

The wet bulb globe temperature (WBGT) is the decisive parameter for evaluating the work stress at heat-exposed working places and the operation and cool-off times involved. Temperature, radiation, relative humidity and air velocity are determined by measuring the dry temperature TT, the natural humid temperature HTN of a psychrometer and the globe temperature GT of a globe thermometer. These are all combined as WBGT.

For measuring TT and HTN a psychrometer with disengageable ventilator (FN A846-WB) must be connected to the input socket M00 and programmed with the measuring ranges  $N_{tc}$  and  $P_{HT}$ . To obtain the natural humid temperature HTN the plexiglass cap of the psychrometer must be removed during the measurement and the ventilator must be switched off using the slide switch.

A globe thermometer (Pt100) (FP A805-GTS) with the measuring ranges  $P_{204}$  and WBGT is required at the socket M01.

For calculating the wet bulb globe temperature (WBGT) the function channel WBGT indicates the wet bulb globe temperature when the correct sensors are connected.



The factor 0.2 for the globe temperature must be programmed as slope correction at the measuring point M012 (WBGT).  
No longer included in V6 (ALMEMO® 2390-5, 2690-8) !

#### Arrangement and programming of the WBGT sensors:

Sensor	Mst	Range	Size	Note
Psychrometer	M00 <sub>1</sub>	$N_{tc}$	TT	Dry temperature of the air, in °C
	M00 <sub>2</sub>	$P_{HT}$	HTN	Natural humid temperature of the air
Pt100-Globe-thermometer	M01 <sub>1</sub>	$P_{204}$	GT	Globe temperature in °C
	M01 <sub>2</sub>	WBGT	WBGT	$0.1 TT + 0.7 HT + 0.2 GT$

A continuous or a cyclic measuring point scan must be run to obtain up-to-date values.

#### Printout sample:

```
01:23:40 00: +070.00 °C  $N_{tc}$  TT
          01: +075.00 °C  $P_{204}$  GT
          10: +030.00 °C  $P_{HT}$  HT
          11: +043.00 °C WBGT
```

### 3.1.5 Infrared Sensors

#### Measuring Principle

Infrared sensors are used for a non-contact measurement of the heat radiation of objects and for indication of the temperature in °C. This measuring method also allows for a scan of temperature measuring points that would not be possible with conventional contact thermometers. Surfaces with a low thermal conduction and body portions with low thermal capacity can be measured with the same high speed of response as moving, inaccessible or live parts without affecting the device under test.

To obtain satisfactory results when using infrared measuring technology it is important to consider the basic relations and influences of the total emissivity, environmental radiation and the beam path.

#### Fundamentals of Thermal Radiation

Every substance, when above absolute zero, provides an electromagnetic radiation. According to Planck's radiation laws a relation exists between the emitted radiation and the temperature of a body.

$$\text{Total radiation: } S = \sigma \cdot T^4 \quad (\text{Stefan-Boltzmann law}) \quad (1)$$

However, this law is only applicable for 'black body radiators' that emit their whole radiation. Real bodies are also called 'grey radiators' that emit only a part of the radiation and that reflect or let through the other part of the radiation. The ratio between the individual emission  $S_o$  of a temperature radiator to the emission of a black body radiator  $S_B$  is called the total emissivity of a thermal radiator:

$$\text{Emissivity: } \varepsilon = S_o / S_B \quad (2)$$

The emissivity plays an important role in non-contact temperature measurements. As the infrared instruments are calibrated with 'black body radiators' it is necessary to consider the emissivity during measurement. The radiation thermometer measures a radiation  $S_M$  that is composed of the characteristic radiation of the device under test  $S_o$  and of the radiation  $S_U$  that is reflected by the background. The radiation  $S_o$  of the object is multiplied with the emissivity factor  $\varepsilon$  and the ambient radiation  $S_A$  is multiplied with the reflection coefficient  $\rho$ :

$$\text{Measuring radiation: } S_M = \varepsilon \cdot S_o + \rho \cdot S_U \quad (3)$$

Using the relation  $\varepsilon + \rho = 1$  the object radiation can finally be determined as:

$$\begin{aligned} \text{Object radiation: } S_o &= 1/\varepsilon \cdot (S_M - S_U) + S_U & (4) \\ \text{particularly: } S_o &\approx 1/\varepsilon \cdot S_M & \text{if object temp. much higher than ambient} \\ S_o &\approx S_U & \text{if object temp. = ambient temperature} \end{aligned}$$

The latter relations explain that the emissivity factor is only playing a secondary



role in closed rooms and with objects with a low temperature. For objects that have a temperature, which is much higher than the ambient temperature, the influence of the background temperature can be neglected.

### Application

Infrared probes are suitable for non-contact temperature measurements on surface in numerous industrial applications. Typical fields of application are, for example, measurements on paper or textile webs, on lacquering lines, coatings and drying processes. Special applications in the electric/electronic field include, for example, finding hot spots on PCBs and contacts. Cold junction measurements on surfaces using thermocouples allow for a determination of the emissivity factor.

3

### Sensor

Photoelectric radiation receivers with high sensitivity and very short response times, as well as thermal detectors with a slightly slower response are available as transducers.

### Emission Factor

The value of the emission factor can, for example, be taken from the table below. With polished or glossy metal surfaces and translucent devices under test, the emission factor is too small for an accurate measurement. However, a blackened measuring point provides an emission factor of 0.9 to 1.0 and can be measured without problems..



We recommend to treat the measuring point with matt black varnish or similar.

**Table of Emission Factors**

The following table provides a guideline for estimating the emissivity of various materials.

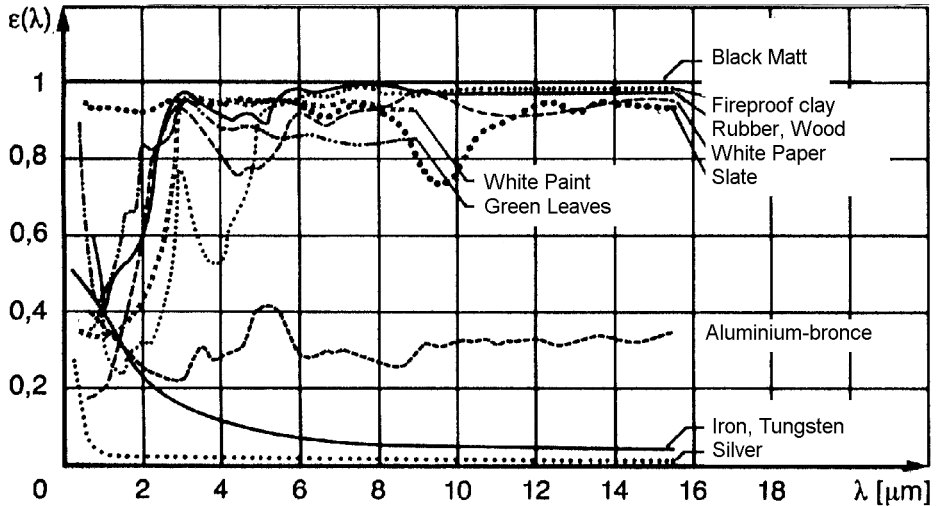


Please note that the emissivity, especially with metals, can largely vary depending on the surface quality, oxidation, rust or presence of dirt, water or oil.

Material	e	Material	e	Material	e
Aluminium		Spring steel	0,87	Nickel	
bright	0,1	Gypsum	0,8 - 0,9	not oxidated	0,15
oxidated	0,2 - 0,4	Glass	0,85 - 0,95	oxidated	0,2 - 0,5
Alumin. oxide	0,42 - 0,26	Rubber	0,95	Paper	0,95
Asbestos	0,96	Graphite	0,7 - 0,8	Plaster	0,91
Asphalt	0,95	Cast iron		Mercury	0,1 - 0,12
Basalt	0,7	not oxidated	0,2	Soot	1
Concrete	0,95	oxidated	0,6 - 0,95	Sand	0,9
Lead oxidated	0,2 - 0,6	turned	0,45	Fireproof clay	0,75
Bitumen	1	Skin	0,99	Snow	0,9
Bread	0,88	Hard board	0,95	Steel	
Tar paper	0,94	Radiator	0,8	sheet with	
Iron		Wood	0,9 - 0,95	rolling skin	0,75
not oxidated	0,1 - 0,2	Limestone	0,95	sheet, bright	0,65
oxidated	0,5 - 0,9	Ceramics	0,95	Turn. parts, bright	0,3
rusted	0,5 - 0,7	Coal	0,8 - 0,9	Textiles	0,95
Stainless steel	0,1 - 0,8	Copper oxidated	0,4 - 0,9	Clay	0,95
Ice	0,98	Plastics	0,9	Water	0,93
Enamel	0,9	Leather	0,94	Cement	0,9
Colour		Marble	0,93	Brick	
mat	0,95	Brass oxidated	0,5	rough	0,93
glossy	0,9	Monel oxidated	0,4	glazed	0,75
Alu colour	0,52			Zinc oxidated	0,1

### Spectral Emissivity of some Materials

The infrared measurement is limited mainly on wavelengths between approximately 0.5 and 20  $\mu\text{m}$ . However, even in this range the emissivity, in certain areas, strongly depends on the wavelength. Therefore, filters are required in some cases.



**Infra-red probe head AMiR FIA628**

The ALMEMO® measuring system provides the infrared transducers FI A628 as photoelectric radiation receivers. All transducers include a chopper setup for the compensation of the ambient temperature.

Sensor:	FIA628-4SS	FIA628-5SS	FIA628-6SS
Measuring range:	-30 ... +100 °C	0 ... +200 °C	0 ... +500 °C
Accuracy:	1°C ± 1.5% of measured value		
Spectral sensitivity:	7 ... 16µm		
Total emissivity:	0.5 ... 1.0		
Response time:	50/320/720/1000 ms		
Output:	0 ... 1V not linear		
Supply voltage:	8 ... 12V through device		

On infra-red sensors FI A628-xSS linearization is programmed in the special connector. These ALMEMO® sensors are thus configured ready-to-connect; they can be plugged directly onto any V6 ALMEMO® measuring instrument (with the exception of the 2390-1/3 and 8390-1/2) in order to read out the measured values.

The emissivity factor can be set on the sensor itself; the necessary input is described in detail in the instructions provided with the probe head.

**Sensors**

Designation	Meas. Range	Meas. Range
FI A628-5SS	0.0... +200.0 °C	Ir1A
FI A628-4SS	-30.0... +100.0 °C	Ir4A
FI A628-6SS	0.0... +500.0 °C	Ir6A

## AMiR FIA908CS - the infra-red probe head with a digital interface



With the AMiR FIA908CS the object temperature (including emissivity factor) is calculated internally and transferred to the measuring instrument in digital form. This is possible with all ALMEMO® devices using the “DIGI” measuring range.

3

### The emissivity factor

With infra-red probe head AMiR FIA908CS the emissivity factor can only be programmed via the ALMEMO® device and only with effect from version V6 and the 2007 update; (this is not at all possible with the 2390-1/-3/-5/-8 and the 8390-1/-2). With these devices, if this infra-red sensor is connected and the appropriate measuring channel is selected, the gain correction function will be replaced by the emissivity factor function and the emissivity factor can thus be input in the sensor. If the focal point lens fitted, the transmission factor of 0.78 will also be considered by means of coding in the connector. The total value can be interrogated via the 4th channel in the connector. (The 4th channel can be activated by means of the “DIGI” measuring range and exponent “-3”).



On older devices and the 2390-1/-3/-5/-8 and the 8390-1/-2, which do not process gain correction as emissivity factor, it is absolutely imperative that this value be deleted; the default setting of 0.95 will then be used instead.

Not only the object temperature but also the sensor head temperature can be displayed on the 2nd channel; (the 2nd channel is activated via the “DIGI” measuring range with “°C” units, exponent “-1”).

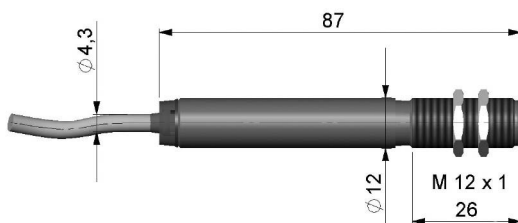
### Technical features:

- Compact, robust, and inexpensive infra-red probe head
- Stainless steel housing, IP 65
- Measuring range from -20 to +350 °C
- Hard-coated glass optics
- Can be used at ambient temperatures up to 75 °C without need for cooling
- Integrated electronics
- Can be connected directly to the ALMEMO® device using an ALMEMO® connector.

## Technical data:

Temperature range	-20 to +350 °C
Spectral range	8 to 14 mm
Optical resolution	FIA908CS 10:1 (distance from measuring field diameter) FIA908CSF 1.2 mm at distance of 10 mm
Emissivity	0.95 fixed, for ALMEMO® devices V6 2450, 2490, 2690, 2890, 8590, 8690, 5690 made from 2007 settable from 0.1 to 1.1
Accuracy	±1.5% or ±1.5 °C (at ambient temperature of 23 ± 5 °C) (whichever is higher)
Reproducibility	±0.75% or ±0.75 °C (at ambient temperature of 23 ± 5 °C) (whichever is higher)
Temperature resolution	0.1 °C (noise equivalent temperature difference, NETD) (at object temperature <100 °C and at >0.2 s)
Response time	0.2 s response time
Protective class	IP 65
Ambient / storage temp.	-20 to +75 °C / -40 to +85 °C
Relative humidity	10 to 95 % non-condensing
Output	ALMEMO® digital
Power supply	5 VDC, approx. 18 mA via ALMEMO® device
Material	Stainless steel
Dimensions	M12x1 thread, 26 mm long, overall length 87 mm (not suitable for hand-held sensors)
Mechanical vibration	IEC 68-2-6: 3G, 11 - 200 Hz, each axis
Shock	IEC 68-2-27: 50G, 11 ms, each axis
Weight	50 grams

## Dimensions:



## Measuring field:

